

UNWINDING AUTOMATIC BRAKE TENSION CONTROL

The purpose of the automatic belt tension control system for starting line unwinder modules is to supply a reliable and stable belt tension conditions to the converting industry. These features will contribute to perform converting processes more reliably and efficiently upstream of the unwinder module.

GENERAL SCHEME

ITEM NO. GENERAL SHCEME DESCRIPTION

- Unwinding machine with automatic web tension control
- 2 Tension control assembly



ITEM NO. TENSION CONTROL ASSEMBLY DESCRIPTION

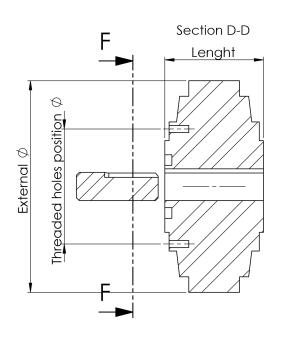
- 1 Unwinding roll shaft
- 2 Safety chucik or standard bushing
- 3 Machine frame
- 4 6 Nm to 50 Nm electromagnertic brake accessory for unwinding web tension control
- 5 Electric box + brake power regulation sensor

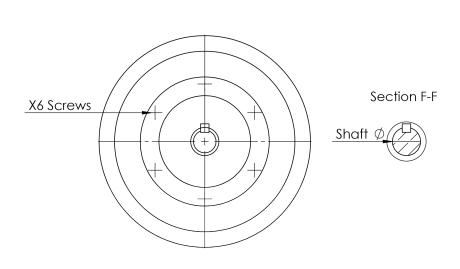






TECHNICAL PARAMETERS





MAIN TECHNICAL PARAMETERS					OVERALL DIMENSIONS				
TORQUE [NM]	VOLTAGE [V]	SPEED [RPM/MIN]	CURRENT [A]	WEIGHT [KG]	EXTERNAL Ø [MM]	LENGHT [MM]	SHAFT Ø [MM]	THREADED HOLES POSITION [MM]	SCREWS
6	24	1000	0,8	2,5	130	60	16	62	M4
12	24	1000	1	4	150	70	20	82	M5
25	24	1000	1,5	6,5	182	78	25	110	M6
50	24	1000	1,8	11,5	219	96	30	130	M8

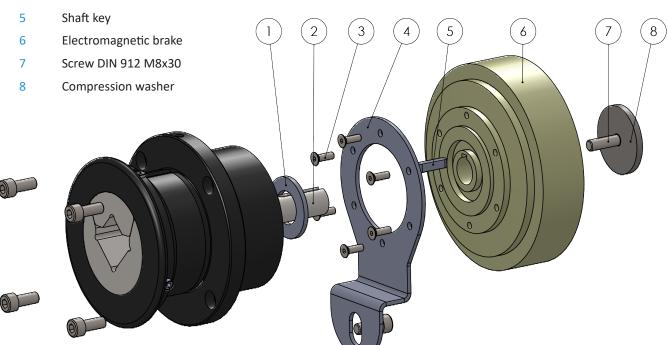




MECHANICAL ASSEMBLY

ITEM NO. TENSION CONTROL ASSEMBLY DESCRIPTION

- Separator washer
- 2 Shaft
- 3 Screw DIN 7991
- 4 Antirotation arm



COMPATIBILITY WITH OTHER EJEMATIC SOLUTIONS

Our Electromagnetic Brake Tension Control guarantees seamless compatibility across the complete range of standard airshafts and machine anchoring systems proudly offered by EJEMATIC:

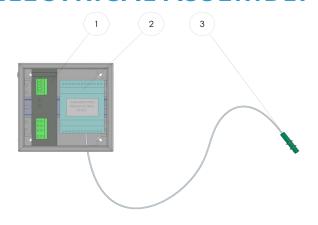
Airshaft type	Double Support	Cantilever	Axial Displacement	
Body Diammeter	Ø69, Ø75, Ø150, Special	Ø69, Ø75, Ø150, Special	Ø69, Ø75, Ø150, Special	
Machine anchor type	Flange & Foot Safety Chucks and Rolling Supports	_	oot Bushings nd Ø45	





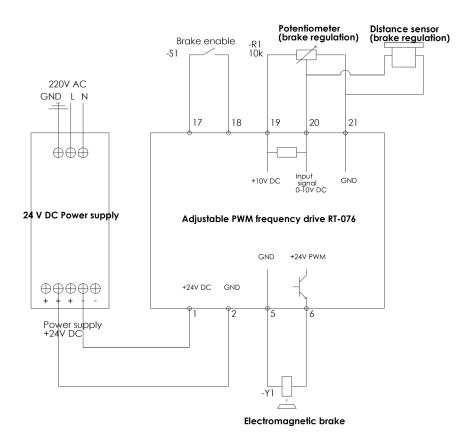
TENSION CONTROL

ELECTRICAL ASSEMBLY



ITEM NO. TENSION CONTROL ASSEMBLY DESCRIPTION

- 1 Power supply
- 2 Adjustable PWM frequency drive
- 3 Brake power regulation sensor:
 - 3.1 Manual potentiometer
 - 3.2 Dancer arm potentiometer or distance sensor or cascade position sensor array
 - 3.3 Distance sensor or pendulum probe sensor
 - 3.4 Load cell.





TENSION CONTROL TYPES

The web tension can be regulated through a manual potencimeter or with different sensor types. Under low-demand unwinding conditions the web tension can be regulated by a manual potentiometer that adjusts the braking power.

When the unwinding conditions are more demanding the web tension is regulated with different sensor types with different technologies involved. The web tension is controlled by a dancer arm and a potentiometer that adjusts the braking power, is controlled by a distance sensor that reads the diameter of the roll and adjusts the braking power or is controlled through a load cell that adjusts the breaking power.

MANUAL

1 MANUAL TENSION CONTROL

The web tension is regulated by a manual potentiometer that adjusts the braking power. It is used in cases where the regulation of brake power is constant., for example in small coils under 300 mm diameter.

COMPONENTS:

- 1 Electromagnetic brake
- 2 Adjustable PWM frequency drive
- 3 24V DC 100W power supply
- 4 Potentiometer
- 5 Electric box







SENSORITZATION

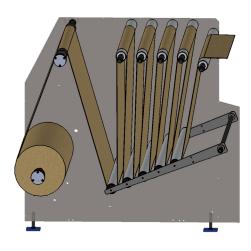
1 TENSION CONTROL THROUGH DANCER ARM

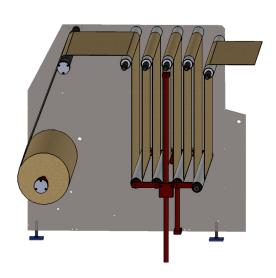
The web tension is controlled by a dancer arm and a potentiometer that adjusts the braking power based on the position of the dancer arm. The weight of the dancer arm determines the web tension. Alternatively to the potentiometer, a distance sensor can be mounted to read the position of the dancer arm.

Alternatively a cascade position sensor array can be mounted to read the position of the dancer arm.

COMPONENTS:

- 1 Linear or angular dancer arm
- 2 Electromagnetic brake
- 3 Adjustable PWM frequency drive
- 4 24V DC 100W power supply
- 5 Dancer arm potentiometer or alternatively distance sensor or alternatively a cascade position sensor array
- 6 Electric box









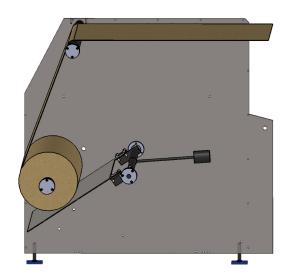
2 TENSION CONTROL THROUGH DISTANCE SENSOR

The web tension is controlled by a distance sensor that reads the diameter of the roll and adjusts the braking power.

Alternatively to the distance sensor, a pendulum type probe can be mounted to read the diameter of the roll.

COMPONENTS:

- 1 Electromagnetic brake
- 2 Adjustable PWM frequency drive
- 3 24V DC 100W power supply
- 4 Distance sensor or alternatively pendulum type probe sensor
- 5 Electric box

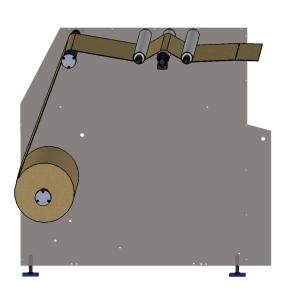


3 TENSION CONTROL THROUGH LOAD CELL

The web tension is controlled by a load cell that adjusts the braking power.

COMPONENTS:

- 1 Electromagnetic brake
- 2 Adjustable PWM frequency drive
- 3 24V DC 100W power supply
- 4 Load cell
- 5 Electric box







UNWINDING MECHANICAL BRAKE TENSION CONTROL

GENERAL SCHEME

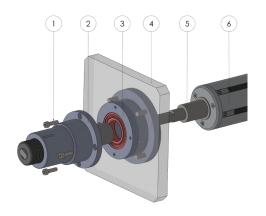
ITEM NO. GENERAL SHCEME DESCRIPTION

- Unwinding machine with mechanical web tension control
- 2 Mechanical brake tension control assembly



ITEM NO. TENSION CONTROL ASSEMBLY DESCRIPTION

- 1 X4 Screw DIN 912 M6x20
- 2 2 Nm to 12 Nm mechanical brake accessory for unwinding web tension control
- 3 Safety chuck or standard bushing
- 4 Air shaft journal end
- 5 Unwinding roll shaft



COMPATIBILITY WITH OTHER EJEMATIC SOLUTIONS

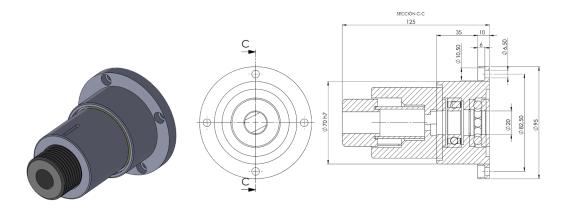
Our Mechanical Brake Tension Control guarantees seamless compatibility across the complete range of standard airshafts and machine anchoring systems proudly offered by EJEMATIC:

Airshaft type	Double Support	Cantilever	Axial Displacement		
Body Diammeter	Ø69, Ø75, Ø150, Special	Ø69, Ø75, Ø150, Special	Ø69, Ø75, Ø150, Special		
Machine anchor type	Flange & Foot Safety Chucks and Rolling Supports	Flange & Foot Bushings Ø35 and Ø45			



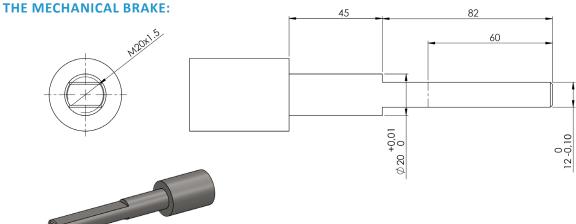


TECHNICAL PARAMETERS



Brake power manual regulation through the nut

REQUIRED JOURNAL END TO ASSEMBLE



TORQUE [NM]	SPEED [RPM/MIN]	WEIGHT [KG]	EXTERNAL Ø [MM]	LENGHT [MM]	SHAFT Ø [MM]	THREADED HOLES POSITION [MM]	SCREWS	PRODUCT REFERENCE
2	1000	1.8	95	125	20	82.5	M6	CTS-MBX-002
4	1000	1.8	95	125	20	82.5	M6	CTS-MBX-004
6	1000	1.8	95	125	20	82.5	M6	CTS-MBX-006
12	1000	1.8	115	130	20	102.5	M6	CTS-MBX-012

